

Multiplexing

by

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Outline of the Lecture



- What is Multiplexing and why is it used ?
- Basic concepts of Multiplexing
- Types of Multiplexing:
 - Frequency Division Multiplexing (FDM)
 - Wavelength Division Multiplexing (WDM)
 - ➤ Time Division Multiplexing (TDM)
 - Synchronous
 - Asynchronous
 - Inverse TDM

Introduction



- To make efficient use of high-speed telecommunications lines, some form of multiplexing is used.
- Multiplexing allows several transmission sources to share a larger transmission capacity.
- Most individual data communicating devices typically require modest data rate, but the media usually has much higher bandwidth.
- Two communicating stations do not utilize the full capacity of a data link.
- The higher the data rate, the most cost effective is the transmission facility.



• When the bandwidth of a medium is greater than individual signals to be transmitted through the channel, a medium can be shared by more than one channel of signals by using Multiplexing.

• For efficiency, the channel capacity can be shared among a number of communicating stations.

• Most common use of multiplexing is in long-haul communication using coaxial cable, microwave and optical fibre.

Basic Concept



- A device known as Multiplexer (MUX) combines 'n' channels for transmission through a single medium or link.
- At the other end a De-multiplexer (DEMUX) is used to separate out the 'n' channels.











- **FDM** can be used with analog signals.
- A number of signals are carried simultaneously on the same medium by allocating to each signal a different frequency band.
- FDM is possible when the useful bandwidth of the transmission medium exceeds the required bandwidth of signals to be transmitted.
- A number of signals can be carried simultaneously if each signal is modulated onto a different carrier frequency and the carrier frequencies are sufficiently separated that the bandwidths of the signals do not significantly overlap.





FDM Multiplexing Process





FDM De-Multiplexing Process

Example





Filter and shift

Guard Band





- A Guard-Band is a narrow frequency range that separates two ranges of wider frequency.
- This ensures that simultaneously used communication channels do not experience interference or cross-talk, which would result in decreased quality for both transmissions.

Applications of FDM



• Transmission of AM/FM Radio broadcasting

• TV broadcasting

• Cable television

Wavelength Division Multiplexing



- Optical fiber medium provides enormous bandwidth.
- WDM is the most viable technology that overcomes the huge opto-electronic bandwidth mismatch.
- WDM optical fiber network comprises optical wavelength switches/routers interconnected by point-to-point fiber links.
- End users may communicate with each other through all-optical (WDM) channels known as *Light-paths*, which may span over more than one fiber links.

WDM





Time Division Multiplexing



- Possible when the bandwidth of the medium exceeds the data rate of digital signals to be transmitted.
- Multiple digital signals can be carried on a single transmission path by interleaving portions of each signal in time.
- Interleaving can be at the bit level or in blocks of bytes.





- The incoming data from each source are briefly buffered.
 - Each buffer is typically one bit or one character in length.
 - The buffers are scanned sequentially to form a composite data stream.
 - The scan operation is sufficiently rapid so that each buffer is emptied before more data can arrive.

Synchronous TDM



- Composite data rate must be at least equal to the sum of the individual data rate.
- The composite signal can be transmitted directly or through a modem.





Frame Synchronization

- In this scheme, typically, one control bit is added to each TDM frame.
- An identifiable pattern of bits, from frame to frame, is used as a "control channel."
- Thus, to synchronize, a receiver compares the incoming bits of one frame position to the expected pattern.
- If the pattern does not match, successive bit positions are searched until the pattern persists over multiple frames.
- Once frame synchronization is established, the receiver continues to monitor the framing bit channel.
- If the pattern breaks down, the receiver must again enter a framing search mode.



Pulse Stuffing

- If each source has a separate clock, any variation among clocks could cause loss of synchronization.
- With pulse stuffing, the outgoing data rate of the multiplexer, excluding framing bits, is higher than the sum of the maximum instantaneous incoming rates.
- The extra capacity is used by stuffing extra dummy bits or pulses into each incoming signal until its rate is raised to that of a locally generated clock signal.
- The stuffed pulses are inserted at fixed locations in the multiplexer frame format so that they may be identified and removed at the de-multiplexer.

Limitations of Synchronous TDM



- In synchronous TDM, many of the time slots in a frame may be wasted.
- The problem is overcame in Statistical / Asynchronous / Intelligent TDM.
- In Statistical TDM, time slots are allocated dynamically on demand.
- It takes the advantage of the fact that not all the attached devices may be transmitting all of the time.

Asynchronous TDM



- As with a synchronous TDM, the statistical multiplexer has a number of I/O lines on one side and a higher-speed multiplexed line on the other. Each I/O line has a buffer associated with it.
- In the case of the statistical multiplexer, there are 'n' I/O lines, but only *k*, where *k* < *n*, time slots available on the TDM frame.
- For input, the function of the multiplexer is to scan the input buffers, collecting data until a frame is filled, and then send the frame.
- On output, the multiplexer receives a frame and distributes the slots of data to the appropriate output buffers.

Synchronous vs Asynchronous



Synchronous vs. Asynchronous TDM



Asynchronous TDM



- Since data arrive from and are distributed to I/O lines unpredictably, *address information* is required to assure proper delivery.
- This leads to more overhead per slot.
- Relative addressing can be used to reduce overhead.

		ADDRESS		DATA				
One source per frame								
Address	Length	Data	٦		[Address	Length	Data

Performance of Asynchronous TDM



- In ATM, the data rate at the output is less than the data rate at the input.
- However, in peak periods the input may exceed capacity.
- Buffers of suitable size may be included to overcome this problem.
- Let 'n' = number of inputs, 'r' = data rate of each source, 'M' = effective capacity of the output, ' α '=mean fraction of time each input is transmitting, $0 < \alpha < 1$.
- Then, a measure of compression is C = M/(nr), bounded by $\alpha < C < 1$.

Inverse Multiplexing



- An inverse multiplexer (IMUX) is a device performing the opposite function of a multiplexer (MUX).
- Instead of allowing one or more low-speed analog or digital input signals (or data streams) to be selected, combined and transmitted at a higher speed on a single shared medium i.e. multiplexing, an inverse multiplexer breaks the combined and related higher speed analog or digital signals into several concurrent lower-speed related signals or data streams.
- Thus, using multiple slower lines, the data stream can be more evenly distributed across all lines.



- The difference between de-multiplexing (DEMUX) and inverse multiplexing is that the output streams of de-multiplexing are unrelated but the output streams of inverse multiplexing are related.
- Just as multiplexers are combined with demultiplexers to create bi-directional data flow, inverse multiplexers may be combined with an inverse DEMUX (i.e. the reverse of an inverse multiplexer).



Thanks!

Figure and slide materials are taken from the following sources:

- 1. W. Stallings, (2010), Data and Computer Communications
- 2. NPTL lecture on Data Communication, by Prof. A. K. Pal, IIT Kharagpur
- 3. B. A. Forouzan, (2013), Data Communication and Networking